



Well-posedness and optimal control for stochastic second grade fluids

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Stochastic second grade fluids equations

We consider the stochastic second grade fluids equations in a bounded and simply connected domain \mathcal{O} of \mathbb{R}^2 with a sufficiently regular boundary Γ

$$\begin{cases} d(\sigma(Y)) = (\nu\Delta Y - \text{curl}(\sigma(Y)) \times Y - \nabla\pi + U) dt + G(t, Y) dW_t, \\ \text{div } Y = 0 \\ Y \cdot \mathbf{n} = 0, & (\mathbf{n} \cdot DY) \cdot \tau = 0 \\ Y(0) = Y_0 \end{cases} \quad (1)$$

$Y = (Y_1, Y_2)$ is the velocity

$$\sigma(Y) = Y - \alpha\Delta Y$$



Functional spaces

Let us introduce the following Hilbert spaces

$$H = \{v \in L^2(\mathcal{O}) \mid \operatorname{div} v = 0 \text{ in } \mathcal{O} \text{ and } v \cdot n = 0 \text{ on } \Gamma\},$$

$$V = \{v \in H^1(\mathcal{O}) \mid \operatorname{div} v = 0 \text{ in } \mathcal{O} \text{ and } v \cdot n = 0 \text{ on } \Gamma\},$$

$$W = \{v \in V \cap H^2(\mathcal{O}) \mid (n \cdot Dv) \cdot \tau = 0 \text{ on } \Gamma\},$$

$$\widetilde{W} = W \cap H^3(\mathcal{O}).$$

$$\|v\|_V^2 = (\sigma(v), v) = \|v\|_2^2 + 2\alpha \|Dv\|_2^2 \approx \|v\|_{H^1}^2$$

$$\|v\|_W^2 = \|\mathbb{P}\sigma(v)\|_2^2 + \|v\|_V^2 \approx \|v\|_{H^2}^2$$

$$\|v\|_{\widetilde{W}} = \|\operatorname{curl} \sigma(v)\|_2^2 + \|v\|_V^2 \approx \|v\|_{H^3}^2$$

Leray projection \mathbb{P} , rate-of-strain tensor $DY = \frac{1}{2} [\nabla Y + \nabla Y^T]$



Well-posedness for the SDE

Theorem

Assume $U \in L^p(\Omega, L^p(0, T; H^1(\mathcal{O})))$, $Y_0 \in L^p(\Omega, V) \cap L^2(\Omega, \widetilde{W})$
for some $4 \leq p < \infty$.

Then there exists a unique solution

$Y \in L^2(\Omega, L^\infty(0, T; \widetilde{W})) \cap L^p(\Omega, L^\infty(0, T; V))$ such that

$$\mathbb{E} \sup_{s \in [0, t]} \|Y(s)\|_V^2 + 8\nu \mathbb{E} \int_0^t \|DY\|_2^2 ds \leq C \left(\mathbb{E} \|Y_0\|_V^2 + \mathbb{E} \|U\|_{L^2(0, t; L^2)}^2 + 1 \right)$$

$$\mathbb{E} \sup_{s \in [0, t]} \|\operatorname{curl} \sigma(Y(s))\|_2^2 \leq C \left(\mathbb{E} \|\operatorname{curl} \sigma(Y_0)\|_2^2 + \mathbb{E} \|U\|_{L^2(0, t; H^1)}^2 + 1 \right),$$

$$\mathbb{E} \sup_{s \in [0, t]} \|Y(s)\|_V^p \leq C \left(\mathbb{E} \|Y_0\|_V^p + \mathbb{E} \|U\|_{L^p(0, t; L^2)}^p + 1 \right).$$



Stability of the solutions

Theorem

Assume that $U_1, U_2 \in L^2(\Omega, L^2(0, T; H^1(\mathcal{O})))$ and

$$Y_1, Y_2 \in L^2(\Omega, L^\infty(0, T; \widetilde{W}))$$

are corresponding solutions of (1). Then there exist constants C , C_3 , such that

$$\mathbb{E} \sup_{s \in [0, t]} \xi_3(s) \|Y_1 - Y_2\|_W^2 \leq C \mathbb{E} \int_0^t \xi_3(s) \|U_1 - U_2\|_2^2 ds$$

where the function ξ is defined as

$$\xi_3(t) = e^{-C_3 \int_0^t (\|Y_1\|_{H^3} + \|Y_2\|_{H^3} + 1) ds}.$$



Control problem

Cost functional

$$J(U, Y_U) = \mathbb{E} \int_0^T L(t, Y_U, U) dt + \mathbb{E} h(Y_U(T)) \quad (2)$$

$$(\mathcal{P}) \begin{cases} \text{minimize} & J(U, Y_U) \\ \text{subject to} & \begin{cases} U \in \mathcal{U}_{ad}^b \\ Y_U \in L^2(\Omega, L^\infty(0, T; H^3(\mathcal{O}))) \text{ solution of} \end{cases} \end{cases} \quad (1)$$

$\mathcal{U}_{ad}^b \subset L^p(\Omega, L^2(0, T; H^1(\mathcal{O})))$, $4 \leq p < \infty$, closed convex and bounded. A standard example is the quadratic cost, where the Lagrangian is defined by

$$L(t, U, Y_U) = \|Y_U - Y_d\|_2^2 + \frac{\lambda}{2} \|U\|_2^2$$

with a desired target field $Y_d \in L^2(\Omega \times \mathcal{O} \times (0, T))$ and some given $\lambda \geq 0$



Main result for the control problem

$\exists (U^*, Y^*)$ a solution for (\mathcal{P}) . In addition, exists a unique solution $(p^*, q^*) \in L^2(0, T; H^2(\mathcal{O})) \cap C([0, T]; H^1(\mathcal{O}))$ to (BSDE)

$$\left\{ \begin{array}{l} d\sigma(p^*) = (-\nu\Delta p^* - \operatorname{curl} \sigma(Y) \times p^* + \operatorname{curl}(\sigma(Y^* \times p^*)) + \nabla\pi - f) \\ \quad - (\nabla_y L(t, U^*, Y^*) + \nabla_y G(t, Y^*)^T q^*) dt + \sigma(q^*) dW_t, \\ \operatorname{div} p^* = 0 \\ p^* \cdot n = 0, \quad (n \cdot Dp^*) \cdot \tau = 0 \\ p^*(T) = h(Y(T)) \end{array} \right. \quad (3)$$

such that the following optimality condition holds

$$\mathbb{E} \int_0^T (p^* + \nabla_x L(t, U^*, Y^*), \Psi - U^*) dt \geq 0 \quad (4)$$

for all $\Psi \in \mathcal{U}_{ad}^b$.



Main idea to deduce the optimality condition

Take (U, Y) and suppose it is optimal pair. Then $\forall \Psi \in \mathcal{U}_{ad}^b$.

$$\left. \frac{dJ(U + \rho(\Psi - U))}{d\rho} \right|_{\rho=0} = \mathbb{E} \int_0^T (\nabla_x L(t, U, Y), \Psi - U) + (\nabla_y L(t, U, Y), Z) \\ + \mathbb{E} (\nabla h(Y(T)), Z(T))_V \geq 0$$

where $Z = D_{\Psi-U} Y(U)$ is the Gâteaux derivative of $U \rightarrow Y$ at point U , in the direction $\Psi - U$

- What is $Z = D_{\Psi-U} Y(U)$?
- Knowing Z , how to define the so-called adjoint state p ?

Verifying

$$\mathbb{E} \int_0^T (\nabla_y L(t, U, Y), Z) + \mathbb{E} (\nabla h(Y(T)), Z(T))_V = \mathbb{E} \int_0^T (p, \Psi - U).$$



Derivative of $U \rightarrow Y = Y_U$

Consider U and $U_\rho = U + \rho\Phi$, $\rho \in (0, 1)$.

If $Y = Y_U$ and $Y_\rho = Y_{U_\rho}$ are the solutions of (1) corresponding to U and U_ρ then

$$Y_\rho = Y + \rho Z + \rho \delta_\rho \quad \text{with} \quad \lim_{\rho \rightarrow 0} \sup_{t \in [0, T]} \|\delta_\rho\|_V^2 = 0 \quad P\text{-a.e.} \quad \omega \in \Omega$$

where $Z \in L^\infty(0, T; W)$ for P -a.e. $\omega \in \Omega$ is the unique solution to

$$\left\{ \begin{array}{l} d\sigma(Z) = (\nu \Delta Z - \text{curl} \sigma(Z) \times Y - \text{curl} \sigma(Y) \times Z - \nabla \pi + \Phi) dt \\ \quad + \nabla_y G(t, Y) Z dW_t \\ \text{div} Z = 0 \\ Z \cdot n = 0, \quad (n \cdot DZ) \cdot \tau = 0 \\ Z(0) = 0 \end{array} \right.$$



Adjoint equation

Let us consider the following backward stochastic equation

$$\left\{ \begin{array}{l} d(\sigma(p), \phi) = (-\nu \Delta p - \operatorname{curl} \sigma(Y) \times p + \operatorname{curl}(\sigma(Y \times p)), \phi) dt \\ \quad - \left(\nabla_y L(t, U, Y) + \nabla_y G(t, Y)^T q, \phi \right) dt + (\sigma(q), \phi) dW_t \\ \operatorname{div} p = 0 \\ p \cdot n = 0, \quad (n \cdot Dp) \cdot \tau = 0 \\ p(T) = \nabla h(Y(T)) \end{array} \right. \quad (6)$$

where $Y = Y_U$

$\exists (p, q) \in L^\infty(0, T; W) \times L^2(0, T; W) \quad P - \text{a.e. in } \Omega$



Duality property

We have

$$\begin{aligned} \mathbb{E} \int_0^T (\Phi, p_n) dt &= \mathbb{E} \int_0^T (\nabla_y L(t, U, Y), Z_n^\Phi) dt \\ &\quad + \mathbb{E} (\sigma(Z_n^\Phi(T)), \nabla h(Y_T)) \end{aligned}$$

for any $\Phi \in L^2(\Omega, L^2(0, T; V))$.



Lack of integrability for Z and p

Given Φ , there exists a unique Z_n^Φ such that

$$\begin{aligned} \mathbb{E} \sup_{s \in [0, t]} \xi_1(s) \|Z_n^\Phi(s)\|_V^2 + \mathbb{E} \int_0^t \xi_1(s) \|Z_n^\Phi\|_V^2 ds \\ \leq C \mathbb{E} \int_0^t \xi_1(s) \|\Phi\|_2^2 ds \end{aligned}$$

$$\mathbb{E} \sup_{s \in [0, t]} \xi_2(s) \|Z_n^\Phi(s)\|_W^2 \leq C \mathbb{E} \int_0^t \xi_2(s) \|\Phi\|_2^2 ds$$

where the functions ξ_1, ξ_2 are defined as

$$\xi_1(t) = e^{-2C_1 \int_0^t \|Y\|_{\widetilde{W}} ds}, \quad \xi_2(t) = e^{-4C_2 \int_0^t \|Y\|_{\widetilde{W}} ds}.$$

and C_1, C_2 are two fixed constants just depending of the domain.



Exponential integrability of the state Y

Assume:

- G is bounded $\|G(t, Y)\|_V^2 \leq L$

- $A = \frac{1}{2\theta_1} \geq C_1$

or $B = \frac{\gamma_2^2}{2\theta_2} \geq C_1$ and \mathcal{O} non axisymmetric,

where $\theta_1, \theta_2, \gamma_1, \bar{\gamma}_1, \gamma_2$ and τ are defined by

$$\theta_1 = 4L\tau^2(1 + \gamma_1^2), \quad \theta_2 = 2Le^{2\varepsilon T}(1 + 2\bar{\gamma}_1^2),$$

$$\gamma_1 = \frac{C_*\nu}{\alpha}\tau, \quad \bar{\gamma}_1 = \frac{K_*}{4\alpha}\tau, \quad \gamma_2 = \frac{C_{**}\nu}{\alpha} \quad \text{and} \quad \tau = Te^{\varepsilon T}.$$

with




$$C_{**} \|u\|_{\widetilde{W}}^2 \leq 2\alpha \|Du\|_2^2 + \|\operatorname{curl} \sigma(u)\|_2^2, \quad \|u\|_{H^1}^2 \leq K_* \|Du\|_2^2$$

Then

$$\mathbb{E} \exp \left\{ C_1 \int_0^t \|Y(s)\|_{\widetilde{W}}^2 ds \right\} < \infty$$



References

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